

TM5 Problem 3 – 24

For $\beta = 0.2 \text{ s}^{-1}$, produce computer plots like those shown in Figure 3-15 for a sinusoidal driven, damped oscillator where $x_p(t)$, $x_c(t)$ and the sum $x(t)$ are shown. Let $k = 1 \text{ kg/s}^2$ and $m = 1 \text{ kg}$. Do this for values of ω_D/ω_S of $1/9$, $1/3$, 1.1 , 3 and 6 . For the $x_c(t)$ solution (Eqn. 3.40, the underdamped case), let the phase angle $\delta = 0$. And the amplitude $A = -1 \text{ m}$. For the $x_p(t)$ solution (Eqn. 3.60), let $F_0/m = 1 \text{ m/s}^2$, but calculate δ . What do you observe about the relative amplitudes of the two solutions as ω_D increases? Why does this occur? For $\omega_D/\omega_S = 6$, let $A = 20 \text{ m/s}^2$ for $x_p(t)$ and produce the plot again.

$$\begin{aligned} \text{In}[1]:= & \text{xc}[t_]:= A * \text{Exp}[-\beta * t] * \text{Cos}[\omega_S * t - \theta] \\ & \text{xp}[t_]:= B * \text{Cos}[\omega_D * t - \phi] \end{aligned}$$

$$B = \frac{\frac{F_0}{m}}{\sqrt{(\omega_N^2 - \omega_D^2)^2 + 4 \beta^2 \omega_D^2}}$$

$$\phi = \text{ArcTan}\left[\frac{2 * \beta * \omega_D}{\omega_N^2 - \omega_D^2}\right]$$

$$\text{Out}[3]= \frac{F_0}{m \sqrt{4 \beta^2 \omega_D^2 + (-\omega_D^2 + \omega_N^2)^2}}$$

$$\text{Out}[4]= \text{ArcTan}\left[\frac{2 \beta \omega_D}{-\omega_D^2 + \omega_N^2}\right]$$

Giving

$$\text{In}[6]:= \text{x}[t_]= \text{xc}[t] + \text{xp}[t]$$

$$\text{Out}[6]= A e^{-t \beta} \text{Cos}[\theta - t \omega_S] + \frac{\text{Cos}\left[\text{ArcTan}\left[\frac{2 \beta \omega_D}{-\omega_D^2 + \omega_N^2}\right] - t \omega_D\right] F_0}{m \sqrt{4 \beta^2 \omega_D^2 + (-\omega_D^2 + \omega_N^2)^2}}$$

Taking values of

$$\begin{aligned} \text{In}[6]:= & \theta = 0; \\ & m = 1; \\ & k = 1; \\ & \beta = 0.2; \\ & A = -1; \\ & F_0 = 1; \end{aligned}$$

$$\omega_N = \sqrt{\frac{k}{m}};$$

$$\omega_S = \sqrt{\omega_N^2 - \beta^2}$$

$$\text{Out}[13]= 0.979796$$

Which gives $\omega_S = 0.979796 \text{ s}^{-1}$. This gives

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$$\begin{aligned} \text{In}[1]:= & \mathbf{xc[t_]} := \mathbf{A * Exp[-\beta * t] * Cos[\omega_S * t - \theta]} \\ & \mathbf{xp[t_]} := \mathbf{B * Cos[\omega_D * t - \phi]} \end{aligned}$$

$$\mathbf{B} = \frac{\frac{F_0}{m}}{\sqrt{(\omega_N^2 - \omega_D^2)^2 + 4 \beta^2 \omega_D^2}}$$

$$\mathbf{\phi} = \mathbf{ArcTan\left[\frac{2 * \beta * \omega_D}{\omega_N^2 - \omega_D^2}\right]}$$

$$\text{Out}[3]= \frac{F_0}{m \sqrt{4 \beta^2 \omega_D^2 + (-\omega_D^2 + \omega_N^2)^2}}$$

$$\text{Out}[4]= \mathbf{ArcTan\left[\frac{2 \beta \omega_D}{-\omega_D^2 + \omega_N^2}\right]}$$

Giving

$$\text{In}[6]:= \mathbf{x[t_]} = \mathbf{xc[t]} + \mathbf{xp[t]}$$

$$\text{Out}[6]= \mathbf{A e^{-t \beta} Cos[\theta - t \omega_S]} + \frac{\mathbf{Cos\left[ArcTan\left[\frac{2 \beta \omega_D}{-\omega_D^2 + \omega_N^2}\right] - t \omega_D\right] F_0}{m \sqrt{4 \beta^2 \omega_D^2 + (-\omega_D^2 + \omega_N^2)^2}}$$

Taking values of

$$\begin{aligned} \text{In}[6]:= & \mathbf{\theta = 0;} \\ & \mathbf{m = 1;} \\ & \mathbf{k = 1;} \\ & \mathbf{\beta = 0.2;} \\ & \mathbf{A = -1;} \\ & \mathbf{F_0 = 1;} \end{aligned}$$

$$\mathbf{\omega_N} = \sqrt{\frac{\mathbf{k}}{\mathbf{m}}};$$

$$\mathbf{\omega_S} = \sqrt{\mathbf{\omega_N^2 - \beta^2}}$$

$$\text{Out}[13]= \mathbf{0.979796}$$

Which gives $\omega_S = 0.979796 \text{ s}^{-1}$. This gives

```
In[14]:= Expand[xc[t]]
Expand[xp[t]]
Expand[x[t]]
```

```
Out[14]= -e-0.2t Cos[0.979796 t]
```

```
Out[15]= 
$$\frac{\text{Cos}\left[\text{ArcTan}\left[\frac{0.4 \omega_D}{1 - \omega_D^2}\right] - t \omega_D\right]}{\sqrt{0.16 \omega_D^2 + (1 - \omega_D^2)^2}}$$

```

```
Out[16]= -e-0.2t Cos[0.979796 t] + 
$$\frac{\text{Cos}\left[\text{ArcTan}\left[\frac{0.4 \omega_D}{1 - \omega_D^2}\right] - t \omega_D\right]}{\sqrt{0.16 \omega_D^2 + (1 - \omega_D^2)^2}}$$

```

To make the plots, first take $\frac{\omega_D}{\omega_S} = \frac{1}{9}$ so that $\omega_D = \frac{\omega_S}{9}$, or

```
In[17]:=  $\omega_S$ 
 $\omega_D = \frac{\omega_S}{9}$ 
Expand[x[t]]
```

```
Out[17]= 0.979796
```

```
Out[18]= 0.108866
```

```
Out[19]= 1.01101 Cos[0.0440403 - 0.108866 t] - e-0.2t Cos[0.979796 t]
```

Plot for $\frac{\omega_D}{\omega_S} = \frac{1}{9}$

```
In[20]:= pxc1 = Plot[xc[t], {t, 0, 35}, BaseStyle →
  {FontFamily → Helvetica, FontSize → 12, FontColor → RGBColor[0, 0.5, 0]},
  PlotRange → {-2, 2}, PlotPoints → 100, PlotStyle →
  {{RGBColor[0, 0.5, 0], Thickness[0.005]}}, PlotLabel → "Transient"]
pxp1 = Plot[xp[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica,
  FontSize → 12, FontColor → RGBColor[0, 0, 0.5]}, PlotRange → {-2, 2},
  PlotPoints → 100, PlotStyle → {{RGBColor[0, 0, 0.5], Thickness[0.005]}},
  PlotLabel → "Steady State"]
px1 = Plot[x[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica, FontSize → 12,
  FontColor → RGBColor[0.5, 0, 0.5]}, PlotRange → {-2, 2}, PlotPoints → 100,
  PlotStyle → {{RGBColor[0.5, 0, 0.5], Thickness[0.005]}}, PlotLabel → "Sum"]
px1color = Plot[x[t], {t, 0, 35}, PlotRange → {-2.5, 2.5},
  PlotPoints → 100, PlotStyle → {{RGBColor[0, 0.5, 0]}];
Show[pxc1, pxp1, px1, PlotLabel → "\!\(\!*SubscriptBox[\(\omega\),
  \(\Delta\)]\) = (1/9)\!\(\!*SubscriptBox[\(\omega\), \(\Sigma\)]\)"]
```

```
In[14]:= Expand[xc[t]]
Expand[xp[t]]
Expand[x[t]]
```

```
Out[14]= -e-0.2t Cos[0.979796 t]
```

```
Out[15]= 
$$\frac{\text{Cos}\left[\text{ArcTan}\left[\frac{0.4 \omega_D}{1 - \omega_D^2}\right] - t \omega_D\right]}{\sqrt{0.16 \omega_D^2 + (1 - \omega_D^2)^2}}$$

```

```
Out[16]= -e-0.2t Cos[0.979796 t] + 
$$\frac{\text{Cos}\left[\text{ArcTan}\left[\frac{0.4 \omega_D}{1 - \omega_D^2}\right] - t \omega_D\right]}{\sqrt{0.16 \omega_D^2 + (1 - \omega_D^2)^2}}$$

```

To make the plots, first take $\frac{\omega_D}{\omega_S} = \frac{1}{9}$ so that $\omega_D = \frac{\omega_S}{9}$, or

```
In[17]:=  $\omega_S$ 
 $\omega_D = \frac{\omega_S}{9}$ 
Expand[x[t]]
```

```
Out[17]= 0.979796
```

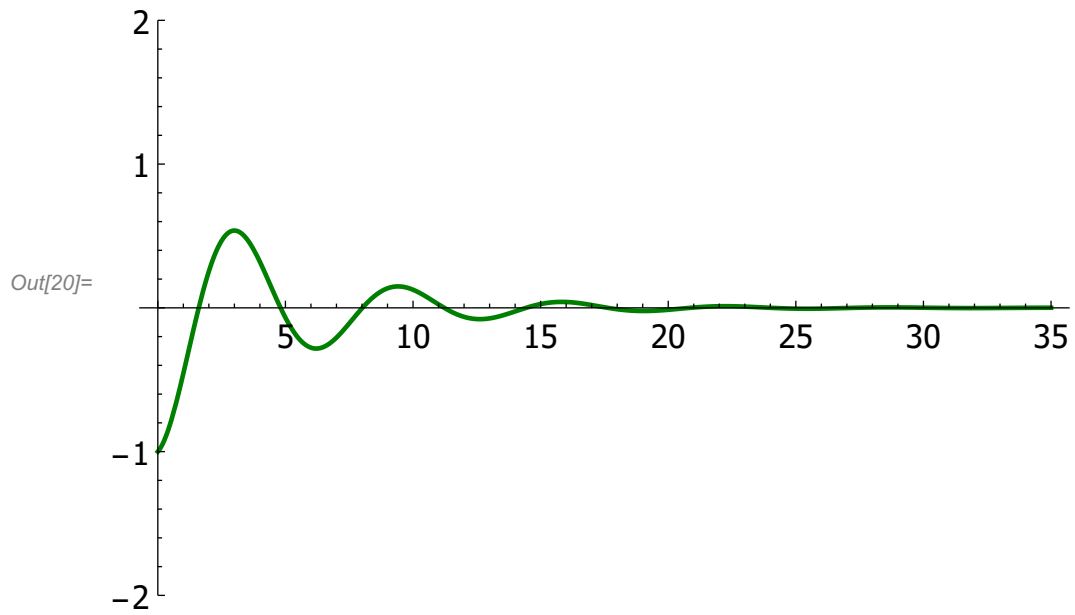
```
Out[18]= 0.108866
```

```
Out[19]= 1.01101 Cos[0.0440403 - 0.108866 t] - e-0.2t Cos[0.979796 t]
```

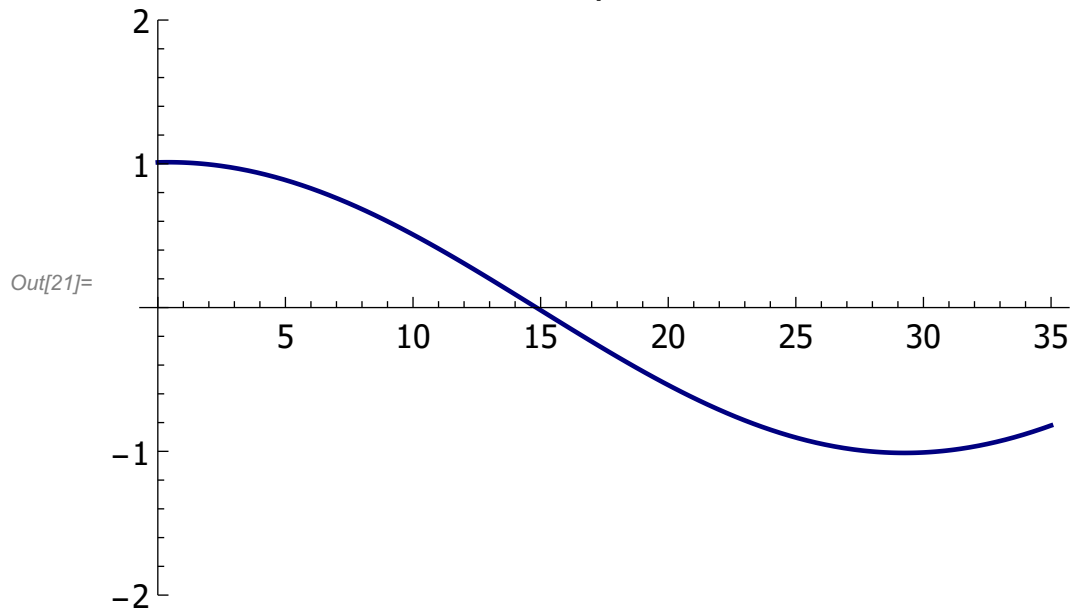
Plot for $\frac{\omega_D}{\omega_S} = \frac{1}{9}$

```
In[20]:= pxc1 = Plot[xc[t], {t, 0, 35}, BaseStyle →
  {FontFamily → Helvetica, FontSize → 12, FontColor → RGBColor[0, 0.5, 0]},
  PlotRange → {-2, 2}, PlotPoints → 100, PlotStyle →
  {{RGBColor[0, 0.5, 0], Thickness[0.005]}}, PlotLabel → "Transient"]
pxp1 = Plot[xp[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica,
  FontSize → 12, FontColor → RGBColor[0, 0, 0.5]}, PlotRange → {-2, 2},
  PlotPoints → 100, PlotStyle → {{RGBColor[0, 0, 0.5], Thickness[0.005]}},
  PlotLabel → "Steady State"]
px1 = Plot[x[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica, FontSize → 12,
  FontColor → RGBColor[0.5, 0, 0.5]}, PlotRange → {-2, 2}, PlotPoints → 100,
  PlotStyle → {{RGBColor[0.5, 0, 0.5], Thickness[0.005]}}, PlotLabel → "Sum"]
px1color = Plot[x[t], {t, 0, 35}, PlotRange → {-2.5, 2.5},
  PlotPoints → 100, PlotStyle → {{RGBColor[0, 0.5, 0]}];
Show[pxc1, pxp1, px1, PlotLabel → "\!\(\(*SubscriptBox[\(\omega\),
  \(\Delta\)]\) = (1/9)\!\(\(*SubscriptBox[\(\omega\), \(\Sigma\)]\)")]
```

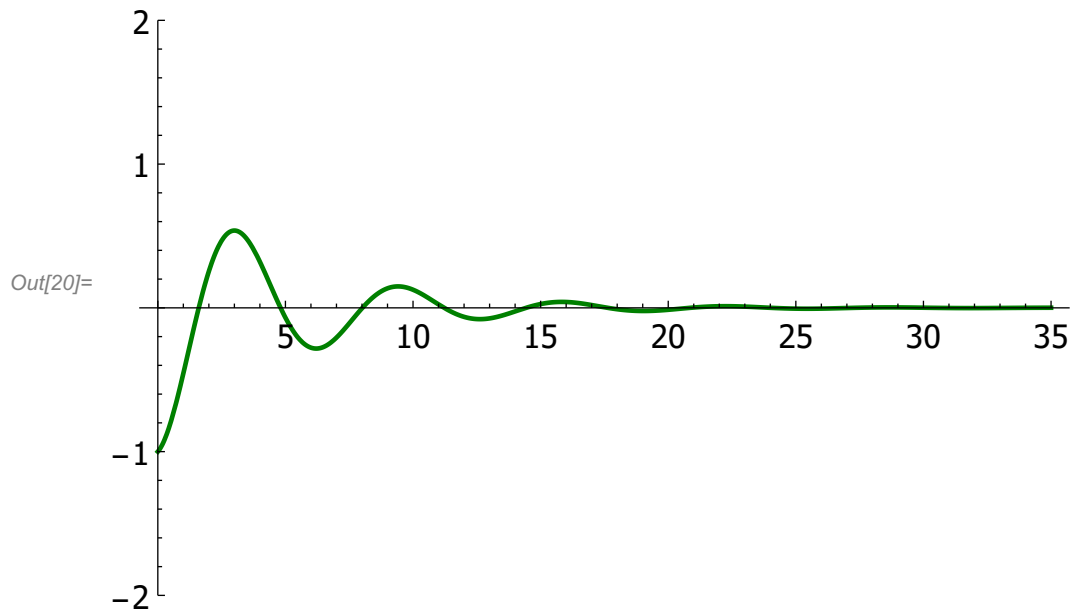
Transient



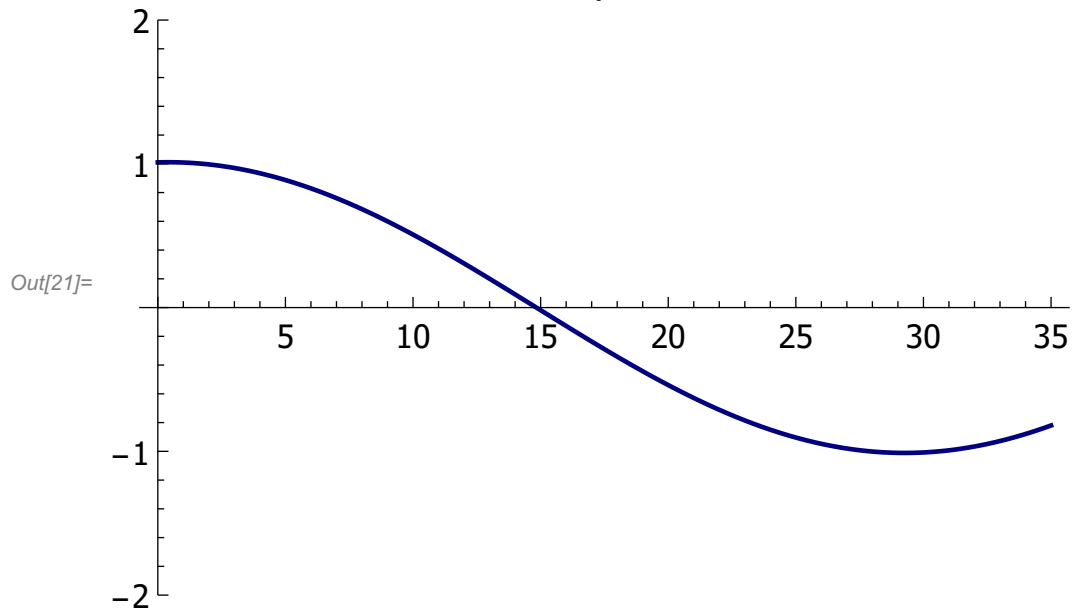
Steady State



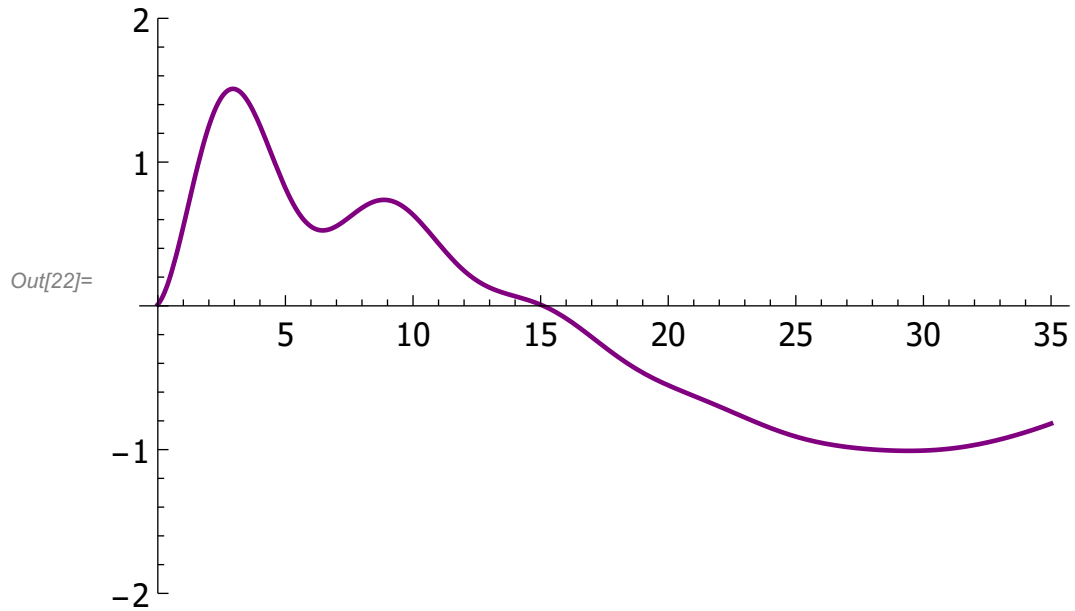
Transient



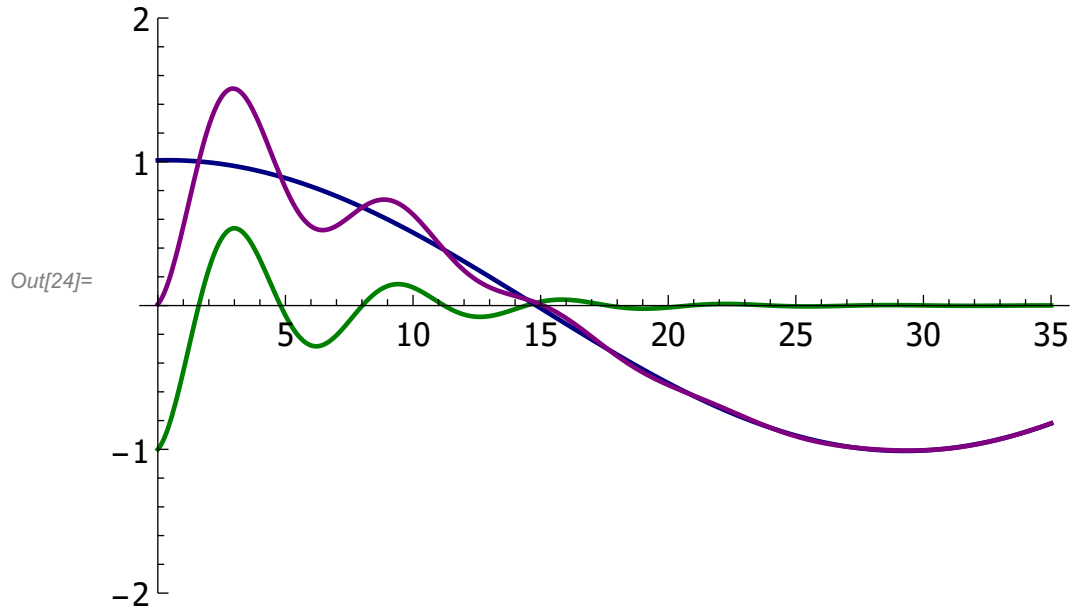
Steady State



Sum



$$\omega_D = (1/9)\omega_S$$



Now take $\frac{\omega_D}{\omega_S} = \frac{1}{3}$ so that $\omega_D = \frac{\omega_S}{3}$, or

In[25]:= ω_S

$$\omega_D = \frac{\omega_S}{3}$$

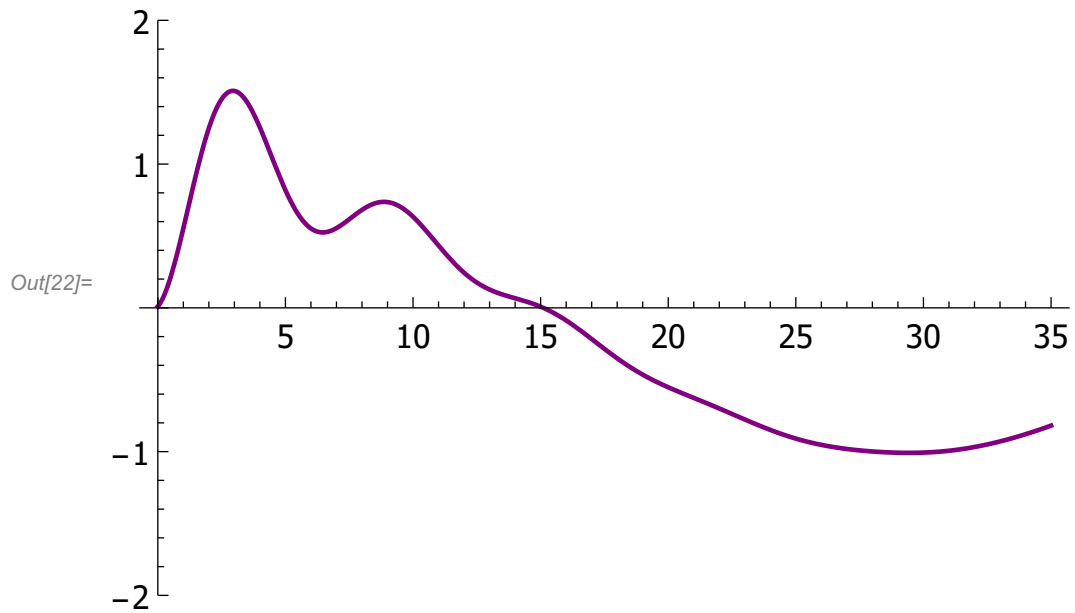
Expand[x[t]]

Out[25]= 0.979796

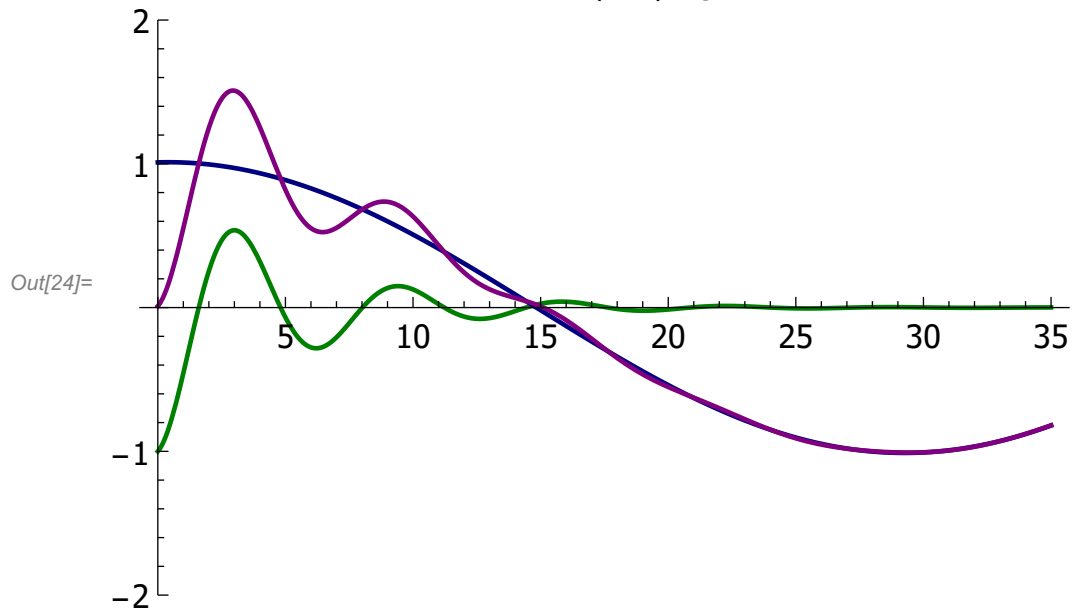
Out[26]= 0.326599

Out[27]= 1.10762 Cos [0.145209 - 0.326599 t] - e^{-0.2 t} Cos [0.979796 t]

Sum



$$\omega_D = (1/9)\omega_S$$



Now take $\frac{\omega_D}{\omega_S} = \frac{1}{3}$ so that $\omega_D = \frac{\omega_S}{3}$, or

In[25]:= ω_S

$$\omega_D = \frac{\omega_S}{3}$$

Expand[x[t]]

Out[25]= 0.979796

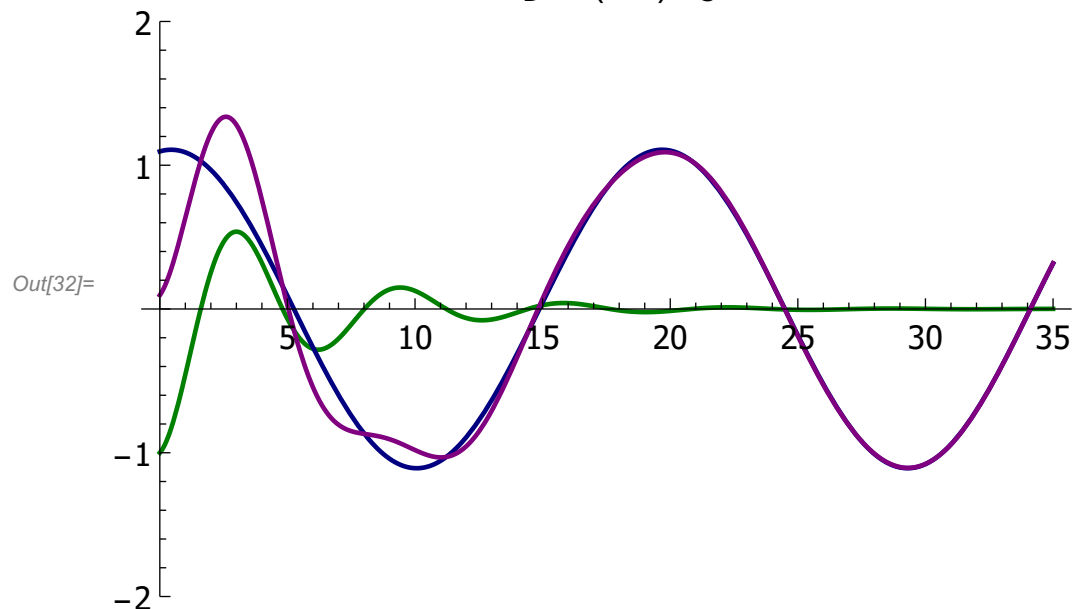
Out[26]= 0.326599

Out[27]= $1.10762 \text{ Cos}[0.145209 - 0.326599 t] - e^{-0.2 t} \text{ Cos}[0.979796 t]$

Plot for $\frac{\omega_D}{\omega_S} = \frac{1}{3}$

```
In[28]:= pxc2 = Plot[xc[t], {t, 0, 35}, BaseStyle →
  {FontFamily → Helvetica, FontSize → 12, FontColor → RGBColor[0, 0.5, 0]},
  PlotRange → {-2, 2}, PlotPoints → 100, PlotStyle →
  {{RGBColor[0, 0.5, 0], Thickness[0.005]}}, PlotLabel → "Transient"];
pxp2 = Plot[xp[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica,
  FontSize → 12, FontColor → RGBColor[0, 0, 0.5]}, PlotRange → {-2, 2},
  PlotPoints → 100, PlotStyle → {{RGBColor[0, 0, 0.5], Thickness[0.005]}},
  PlotLabel → "Steady State"];
px2 = Plot[x[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica, FontSize → 12,
  FontColor → RGBColor[0.5, 0, 0.5]}, PlotRange → {-2, 2}, PlotPoints → 100,
  PlotStyle → {{RGBColor[0.5, 0, 0.5], Thickness[0.005]}}, PlotLabel → "Sum"];
px2color = Plot[x[t], {t, 0, 35}, PlotRange → {-2.5, 2.5},
  PlotPoints → 100, PlotStyle → {{RGBColor[0.5, 0.5, 0]}},
  Show[pxc2, pxp2, px2, PlotLabel → "\!\(\*\SubscriptBox[\(\omega\),
  \(\Delta\)]\) = (1/3)\!\(\*\SubscriptBox[\(\omega\), \(\Sigma\)]\)"]
```

$$\omega_D = (1/3)\omega_S$$

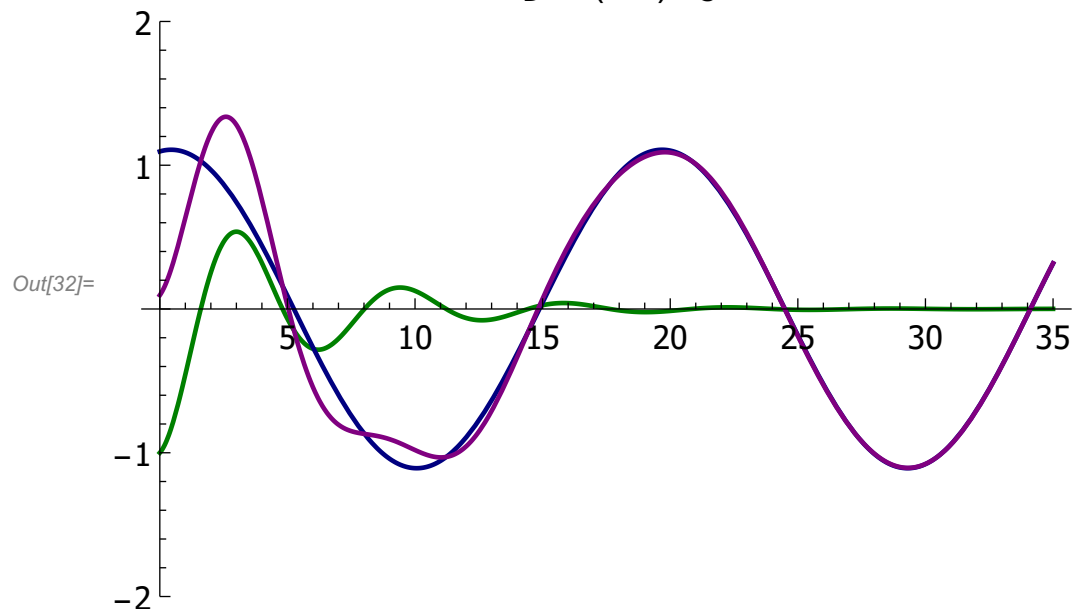


Next take $\frac{\omega_D}{\omega_S} = 1.1$ so that $\omega_D = 1.1 \omega_S$, or

Plot for $\frac{\omega_D}{\omega_S} = \frac{1}{3}$

```
In[28]:= pxc2 = Plot[xc[t], {t, 0, 35}, BaseStyle →
  {FontFamily → Helvetica, FontSize → 12, FontColor → RGBColor[0, 0.5, 0]},
  PlotRange → {-2, 2}, PlotPoints → 100, PlotStyle →
  {{RGBColor[0, 0.5, 0], Thickness[0.005]}}, PlotLabel → "Transient"];
pxp2 = Plot[xp[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica,
  FontSize → 12, FontColor → RGBColor[0, 0, 0.5]}, PlotRange → {-2, 2},
  PlotPoints → 100, PlotStyle → {{RGBColor[0, 0, 0.5], Thickness[0.005]}},
  PlotLabel → "Steady State"];
px2 = Plot[x[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica, FontSize → 12,
  FontColor → RGBColor[0.5, 0, 0.5]}, PlotRange → {-2, 2}, PlotPoints → 100,
  PlotStyle → {{RGBColor[0.5, 0, 0.5], Thickness[0.005]}}, PlotLabel → "Sum"];
px2color = Plot[x[t], {t, 0, 35}, PlotRange → {-2.5, 2.5},
  PlotPoints → 100, PlotStyle → {{RGBColor[0.5, 0.5, 0]}},
  Show[pxc2, pxp2, px2, PlotLabel → "\!\(\*\SubscriptBox[\(\omega\),
  \(\Delta\)]\) = (1/3)\!\(\*\SubscriptBox[\(\omega\), \(\Sigma\)]\)"]
```

$$\omega_D = (1/3)\omega_S$$



Next take $\frac{\omega_D}{\omega_S} = 1.1$ so that $\omega_D = 1.1 \omega_S$, or

Next take $\frac{\omega_D}{\omega_S} = 3$ so that $\omega_D = 3 \omega_S$, or

```
In[41]:=  $\omega_S$ 
 $\omega_D = 3 * \omega_S$ 
Expand[x[t]]
```

Out[41]= 0.979796

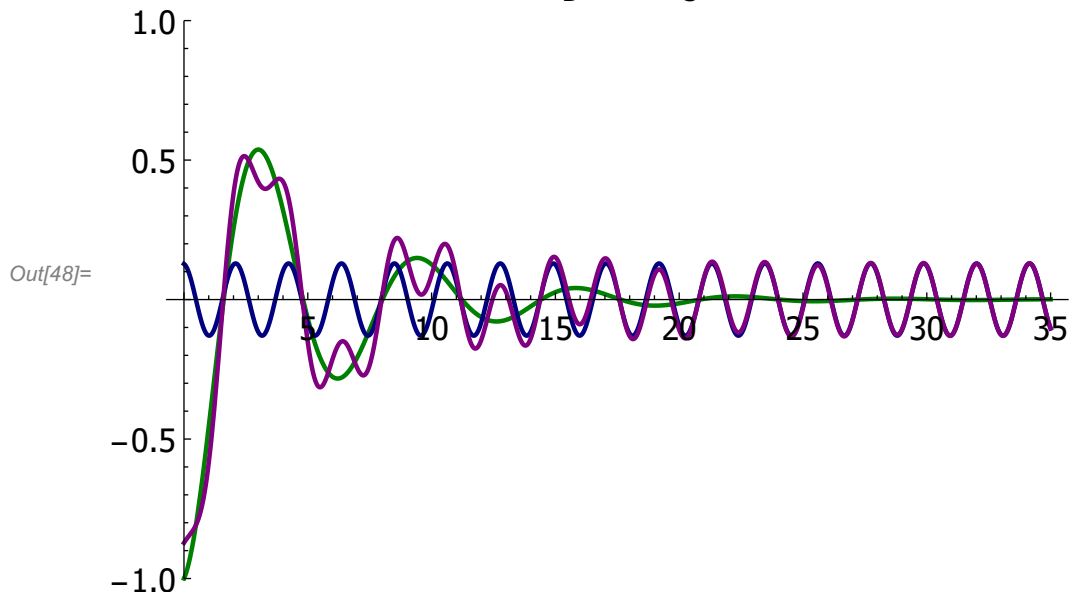
Out[42]= 2.93939

Out[43]= $-e^{-0.2t} \cos[0.979796 t] + 0.129367 \cos[0.152697 + 2.93939 t]$

Plot for $\frac{\omega_D}{\omega_S} = 3$

```
In[44]:= pxc4 = Plot[xc[t], {t, 0, 35}, BaseStyle →
  {FontFamily → Helvetica, FontSize → 12, FontColor → RGBColor[0, 0.5, 0]},
  PlotRange → {-1, 1}, PlotPoints → 100, PlotStyle →
  {{RGBColor[0, 0.5, 0], Thickness[0.005]}}, PlotLabel → "Transient"];
pxp4 = Plot[xp[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica,
  FontSize → 12, FontColor → RGBColor[0, 0, 0.5]}, PlotRange → {-1, 1},
  PlotPoints → 100, PlotStyle → {{RGBColor[0, 0, 0.5], Thickness[0.005]}},
  PlotLabel → "Steady State"];
px4 = Plot[x[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica, FontSize → 12,
  FontColor → RGBColor[0.5, 0, 0.5]}, PlotRange → {-1, 1}, PlotPoints → 100,
  PlotStyle → {{RGBColor[0.5, 0, 0.5], Thickness[0.005]}}, PlotLabel → "Sum"];
px4color = Plot[x[t], {t, 0, 35}, PlotRange → {-2.5, 2.5},
  PlotPoints → 100, PlotStyle → {{RGBColor[0.5, 0, 0.5]}];
Show[pxc4, pxp4, px4, PlotLabel → "\!\(\(*SubscriptBox[\(\omega\),
  \(\mathcal{D}\)]\) = 3\!\(\(*SubscriptBox[\(\omega\), \(\mathcal{S}\)]\)")]
```

$$\omega_D = 3\omega_S$$



Next take $\frac{\omega_D}{\omega_S} = 3$ so that $\omega_D = 3 \omega_S$, or

```
In[41]:=  $\omega_S$ 
 $\omega_D = 3 * \omega_S$ 
Expand[x[t]]
```

Out[41]= 0.979796

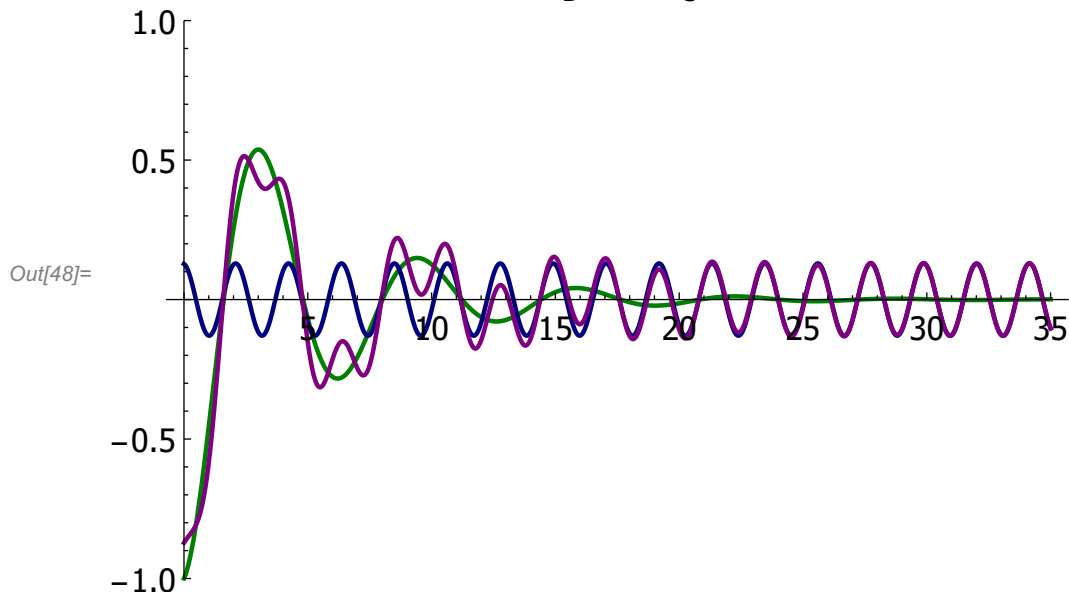
Out[42]= 2.93939

Out[43]= $-e^{-0.2t} \cos[0.979796 t] + 0.129367 \cos[0.152697 + 2.93939 t]$

Plot for $\frac{\omega_D}{\omega_S} = 3$

```
In[44]:= pxc4 = Plot[xc[t], {t, 0, 35}, BaseStyle ->
{FontFamily -> Helvetica, FontSize -> 12, FontColor -> RGBColor[0, 0.5, 0]},
PlotRange -> {-1, 1}, PlotPoints -> 100, PlotStyle ->
{{RGBColor[0, 0.5, 0], Thickness[0.005]}}, PlotLabel -> "Transient"];
pxp4 = Plot[xp[t], {t, 0, 35}, BaseStyle -> {FontFamily -> Helvetica,
FontSize -> 12, FontColor -> RGBColor[0, 0, 0.5]}, PlotRange -> {-1, 1},
PlotPoints -> 100, PlotStyle -> {{RGBColor[0, 0, 0.5], Thickness[0.005]}},
PlotLabel -> "Steady State"];
px4 = Plot[x[t], {t, 0, 35}, BaseStyle -> {FontFamily -> Helvetica, FontSize -> 12,
FontColor -> RGBColor[0.5, 0, 0.5]}, PlotRange -> {-1, 1}, PlotPoints -> 100,
PlotStyle -> {{RGBColor[0.5, 0, 0.5], Thickness[0.005]}}, PlotLabel -> "Sum"];
px4color = Plot[x[t], {t, 0, 35}, PlotRange -> {-2.5, 2.5},
PlotPoints -> 100, PlotStyle -> {{RGBColor[0.5, 0, 0.5]}},
Show[pxc4, pxp4, px4, PlotLabel -> "\!\(\(*SubscriptBox[\(\omega\),
\(\mathcal{D}\)]\)\) = 3\!\(\(*SubscriptBox[\(\omega\), \(\mathcal{S}\)]\)\)"]
```

$$\omega_D = 3\omega_S$$



Next take $\frac{\omega_D}{\omega_S} = 6$ so that $\omega_D = 6\omega_S$, or

```
In[67]:=  $\omega_S$ 
 $\omega_D = 6 * \omega_S$ 
Expand[x[t]]
```

```
Out[67]= 0.979796
```

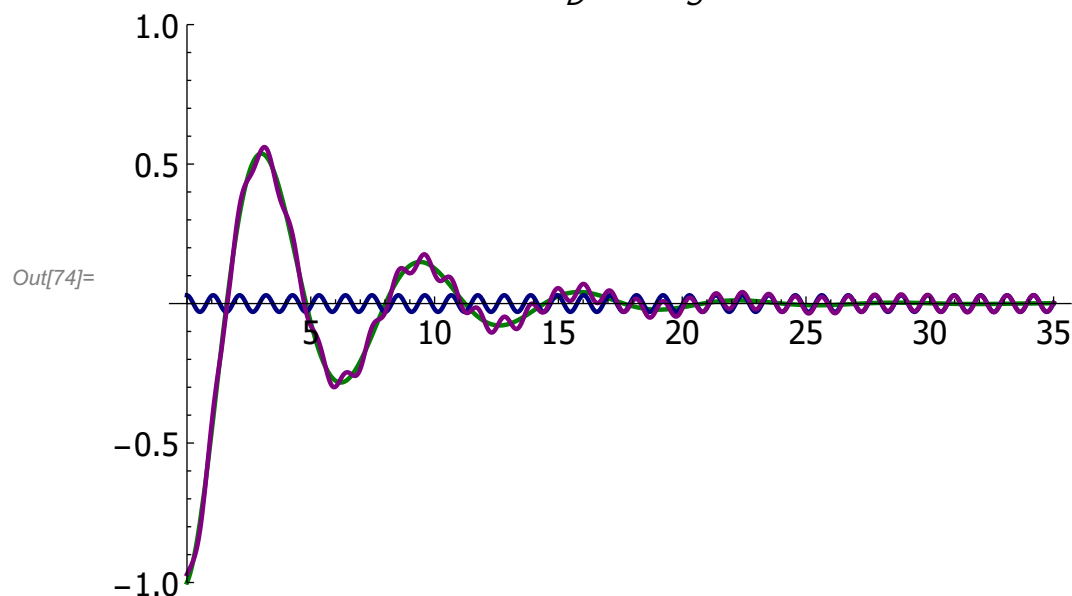
```
Out[68]= 5.87878
```

```
Out[69]=  $-e^{-0.2t} \cos[0.979796 t] + 0.0297245 \cos[0.0699545 + 5.87878 t]$ 
```

Plot for $\frac{\omega_D}{\omega_S} = 6$

```
In[70]:= pxc5 = Plot[xc[t], {t, 0, 35}, BaseStyle →
{FontFamily → Helvetica, FontSize → 12, FontColor → RGBColor[0, 0.5, 0]},
PlotRange → {-1, 1}, PlotPoints → 100, PlotStyle →
{{RGBColor[0, 0.5, 0], Thickness[0.005]}}, PlotLabel → "Transient"];
pxp5 = Plot[xp[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica,
FontSize → 12, FontColor → RGBColor[0, 0, 0.5]}, PlotRange → {-1, 1},
PlotPoints → 100, PlotStyle → {{RGBColor[0, 0, 0.5], Thickness[0.005]}},
PlotLabel → "Steady State"];
px5 = Plot[x[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica, FontSize → 12,
FontColor → RGBColor[0.5, 0, 0.5]}, PlotRange → {-1, 1}, PlotPoints → 100,
PlotStyle → {{RGBColor[0.5, 0, 0.5], Thickness[0.005]}}, PlotLabel → "Sum"];
px5color = Plot[x[t], {t, 0, 35}, PlotRange → {-2.5, 2.5},
PlotPoints → 100, PlotStyle → {{RGBColor[1, 0, 0]}},
Show[pxc5, pxp5, px5, PlotLabel → "\!\(\*\SubscriptBox[\(\omega\),
\(\Delta\)]\) = 6\!\(\*\SubscriptBox[\(\omega\), \(\Sigma\)]\)"]
```

$$\omega_D = 6\omega_S$$



The amplitude of the steady-state term can be seen to increase as ω_D approaches the value of ω_S then decrease as ω_D gets much larger than the value of ω_S . This is due to the dependence of the

Next take $\frac{\omega_D}{\omega_S} = 6$ so that $\omega_D = 6 \omega_S$, or

```
In[67]:=  $\omega_S$ 
 $\omega_D = 6 * \omega_S$ 
Expand[x[t]]
```

```
Out[67]= 0.979796
```

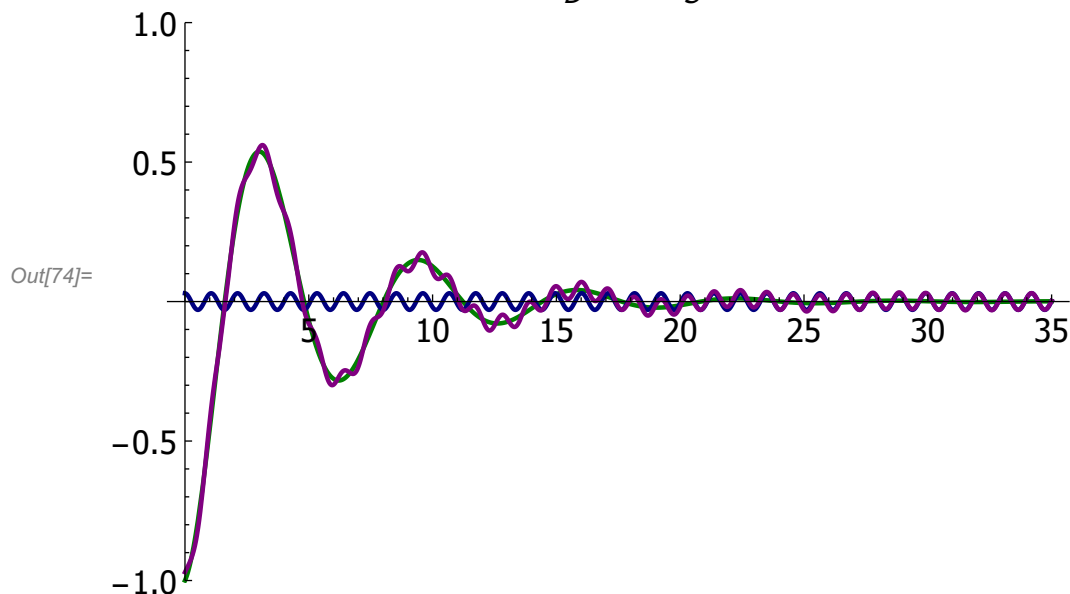
```
Out[68]= 5.87878
```

```
Out[69]=  $-e^{-0.2t} \cos[0.979796 t] + 0.0297245 \cos[0.0699545 + 5.87878 t]$ 
```

Plot for $\frac{\omega_D}{\omega_S} = 6$

```
In[70]:= pxc5 = Plot[xc[t], {t, 0, 35}, BaseStyle →
{FontFamily → Helvetica, FontSize → 12, FontColor → RGBColor[0, 0.5, 0]},
PlotRange → {-1, 1}, PlotPoints → 100, PlotStyle →
{{RGBColor[0, 0.5, 0], Thickness[0.005]}}, PlotLabel → "Transient"];
pxp5 = Plot[xp[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica,
FontSize → 12, FontColor → RGBColor[0, 0, 0.5]}, PlotRange → {-1, 1},
PlotPoints → 100, PlotStyle → {{RGBColor[0, 0, 0.5], Thickness[0.005]}},
PlotLabel → "Steady State"];
px5 = Plot[x[t], {t, 0, 35}, BaseStyle → {FontFamily → Helvetica, FontSize → 12,
FontColor → RGBColor[0.5, 0, 0.5]}, PlotRange → {-1, 1}, PlotPoints → 100,
PlotStyle → {{RGBColor[0.5, 0, 0.5], Thickness[0.005]}}, PlotLabel → "Sum"];
px5color = Plot[x[t], {t, 0, 35}, PlotRange → {-2.5, 2.5},
PlotPoints → 100, PlotStyle → {{RGBColor[1, 0, 0]}},
Show[pxc5, pxp5, px5, PlotLabel → "\!\(\*\SubscriptBox[\(\omega\),
\(\mathcal{D}\)]\) = 6\!\(\*\SubscriptBox[\(\omega\), \(\mathcal{S}\)]\)"]
```

$$\omega_D = 6\omega_S$$



The amplitude of the steady-state term can be seen to increase as ω_D approaches the value of ω_S then decrease as ω_D gets much larger than the value of ω_S . This is due to the dependence of the 8

steady-state amplitude on the frequencies

$$H = \frac{\frac{F_0}{m}}{\sqrt{(\omega_N^2 - \omega_D^2)^2 + 4\beta^2 \omega_D^2}}$$

We can factor out ω_D to show this dependence:

$$H = \frac{\frac{F_0}{m}}{\omega_D \sqrt{\left(\frac{\omega_N^2}{\omega_D^2} - 1\right)^2 + 4\beta^2}}$$

This shows that as the steady-state frequency increases, its amplitude decreases.

For $\omega_D/\omega_S = 6$, let $A = 20 \text{ m/s}^2$ (this is F_0 in my expression) for $x_p(t)$ and produce the plot again. Also reduce the number of cycles because it gets too crowded.

Taking values of

$$\text{In}[7]:= \theta = 0;$$

$$m = 1;$$

$$k = 1;$$

$$\beta = 0.2;$$

$$A = -1;$$

$$B = 1;$$

$$F_0 = 20;$$

$$\omega_N = \sqrt{\frac{k}{m}};$$

$$\omega_S = \sqrt{\omega_N^2 - \beta^2};$$

$$\text{In}[16]:= \text{Expand}[xc[t]]$$

$$\text{Expand}[xp[t]]$$

$$\text{Expand}[x[t]]$$

$$\text{Out}[16]= -e^{-0.2t} \text{Cos}[0.979796 t]$$

$$\text{Out}[17]= \text{Cos}\left[\text{ArcTan}\left[\frac{0.4 \omega_D}{1 - \omega_D^2}\right] - t \omega_D\right]$$

$$\text{Out}[18]= -e^{-0.2t} \text{Cos}[0.979796 t] + \frac{20 \text{Cos}\left[\text{ArcTan}\left[\frac{0.4 \omega_D}{1 - \omega_D^2}\right] - t \omega_D\right]}{\sqrt{0.16 \omega_D^2 + (1 - \omega_D^2)^2}}$$

Plot this for $\omega_D = 6 \omega_S$, or

steady-state amplitude on the frequencies

$$H = \frac{\frac{F_0}{m}}{\sqrt{(\omega_N^2 - \omega_D^2)^2 + 4\beta^2 \omega_D^2}}.$$

We can factor out ω_D to show this dependence:

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For $\omega_D/\omega_S = 6$, let $A = 20 \text{ m/s}^2$ (this is F_0 in my expression) for $x_p(t)$ and produce the plot again. Also reduce the number of cycles because it gets too crowded.

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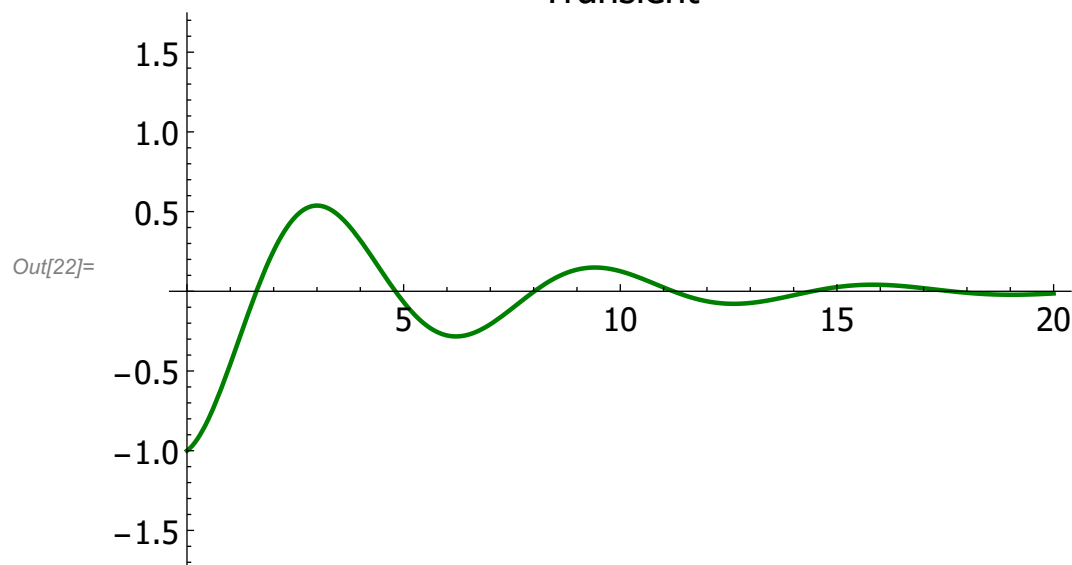
$$\text{Out}[18]= -e^{-0.2t} \text{Cos}[0.979796 t] + \frac{20 \text{Cos}\left[\text{ArcTan}\left[\frac{0.4 \omega_D}{1 - \omega_D^2}\right] - t \omega_D\right]}{\sqrt{0.16 \omega_D^2 + (1 - \omega_D^2)^2}}$$

Plot this for $\omega_D = 6 \omega_S$, or

```
In[19]:=  $\omega_s$ 
 $\omega_D = 6 * \omega_s$ 
Expand[x[t]]
Out[19]= 0.979796
Out[20]= 5.87878
Out[21]=  $-e^{-0.2t} \cos[0.979796 t] + 0.59449 \cos[0.0699545 + 5.87878 t]$ 
```

```
In[22]:= pxc6 = Plot[xc[t], {t, 0, 20}, BaseStyle →
  {FontFamily → Helvetica, FontSize → 12, FontColor → RGBColor[0, 0.5, 0]},
  PlotRange → {-1.75, 1.75}, PlotPoints → 100, PlotStyle →
  {{RGBColor[0, 0.5, 0], Thickness[0.005]}}, PlotLabel → "Transient"]
pxp6 = Plot[xp[t], {t, 0, 20}, BaseStyle → {FontFamily → Helvetica,
  FontSize → 12, FontColor → RGBColor[0, 0, 0.5]}, PlotRange → {-1.75, 1.75},
  PlotPoints → 100, PlotStyle → {{RGBColor[0, 0, 0.5], Thickness[0.005]}},
  PlotLabel → "Steady State"]
px6 = Plot[x[t], {t, 0, 20}, BaseStyle →
  {FontFamily → Helvetica, FontSize → 12, FontColor → RGBColor[0.5, 0, 0.5]},
  PlotRange → {-1.75, 1.75}, PlotPoints → 100,
  PlotStyle → {{RGBColor[0.5, 0, 0.5], Thickness[0.005]}}, PlotLabel → "Sum"]
Show[pxc6, pxp6, px6, PlotLabel → "\!\(\*\SubscriptBox[\(\omega\),
  \(\Delta\)]\) = 6\!\(\*\SubscriptBox[\(\omega\), \(\Sigma\)]\)"]
```

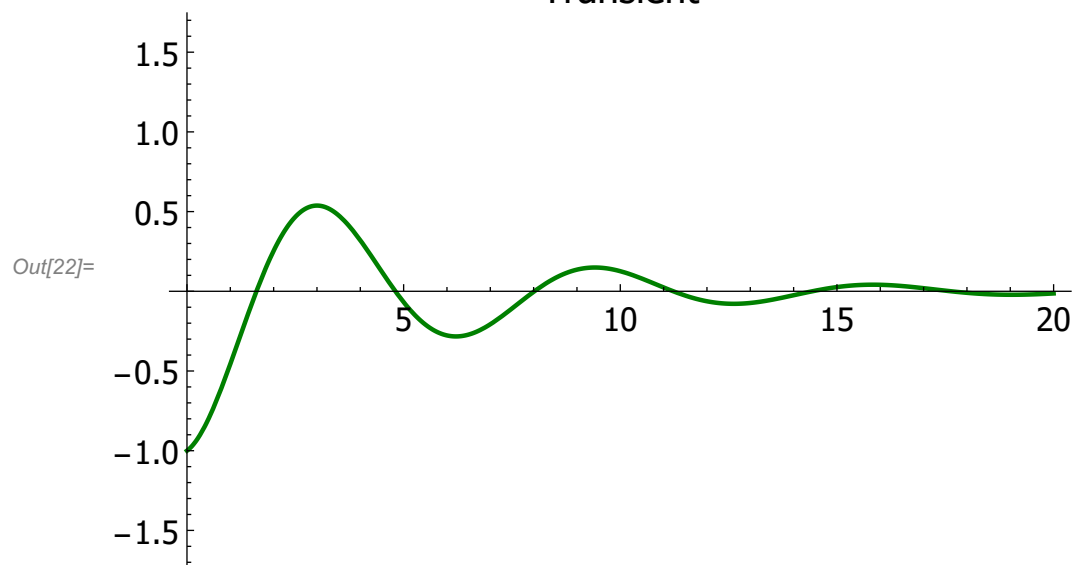
Transient



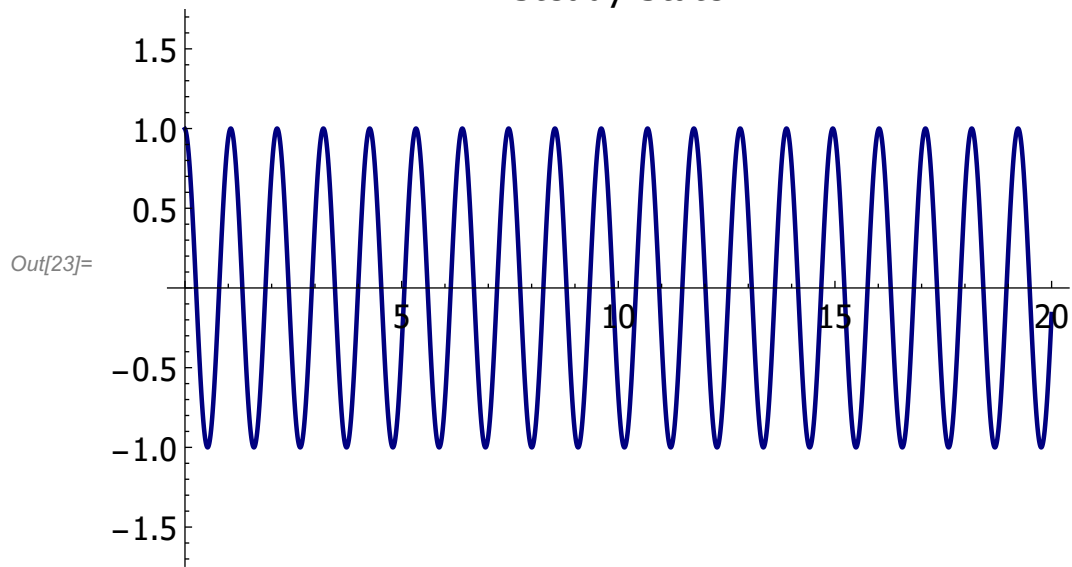
```
In[19]:=  $\omega_s$ 
 $\omega_D = 6 * \omega_s$ 
Expand[x[t]]
Out[19]= 0.979796
Out[20]= 5.87878
Out[21]=  $-e^{-0.2t} \cos[0.979796 t] + 0.59449 \cos[0.0699545 + 5.87878 t]$ 
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  {FontFamily → Helvetica, FontSize → 12, FontColor → RGBColor[0, 0.5, 0]},
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pxp6 = Plot[xp[t], {t, 0, 20}, BaseStyle → {FontFamily → Helvetica,
  FontSize → 12, FontColor → RGBColor[0, 0, 0.5]}, PlotRange → {-1.75, 1.75},
  PlotPoints → 100, PlotStyle → {{RGBColor[0, 0, 0.5], Thickness[0.005]}},
  PlotLabel → "Steady State"]
px6 = Plot[x[t], {t, 0, 20}, BaseStyle →
  {FontFamily → Helvetica, FontSize → 12, FontColor → RGBColor[0.5, 0, 0.5]},
  PlotRange → {-1.75, 1.75}, PlotPoints → 100,
  PlotStyle → {{RGBColor[0.5, 0, 0.5], Thickness[0.005]}}, PlotLabel → "Sum"]
Show[pxc6, pxp6, px6, PlotLabel → "\!\(\*\SubscriptBox[\(\omega\),
  \(\Delta\)]\) = 6\!\(\*\SubscriptBox[\(\omega\), \(\Sigma\)]\)"]
```

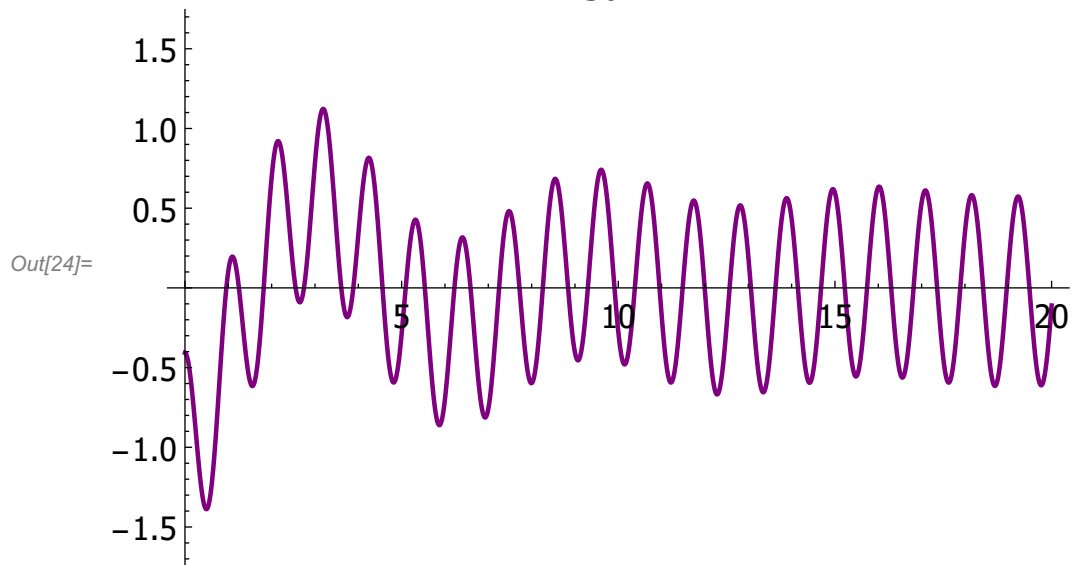
Transient



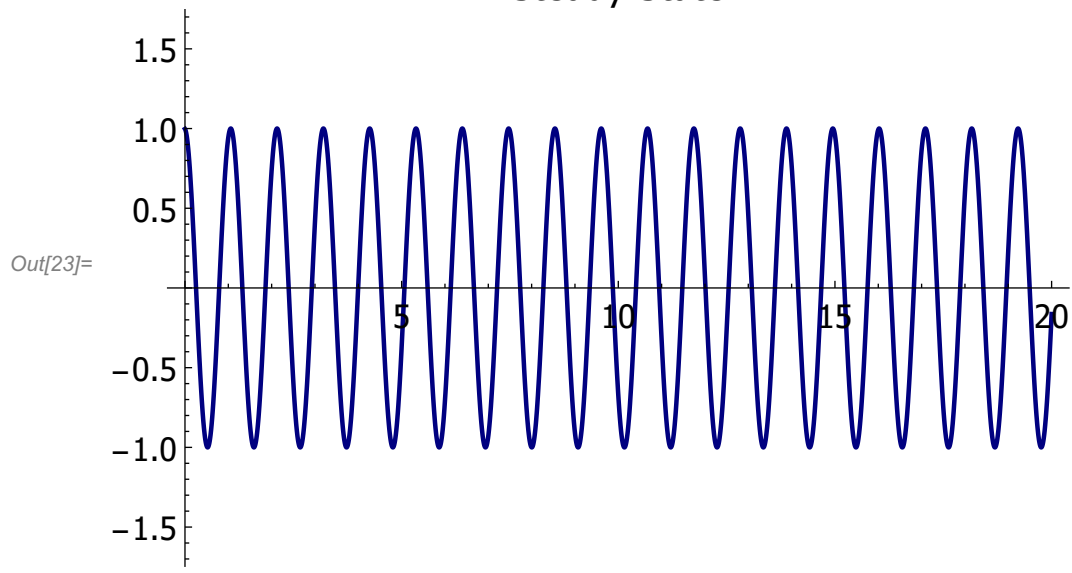
Steady State



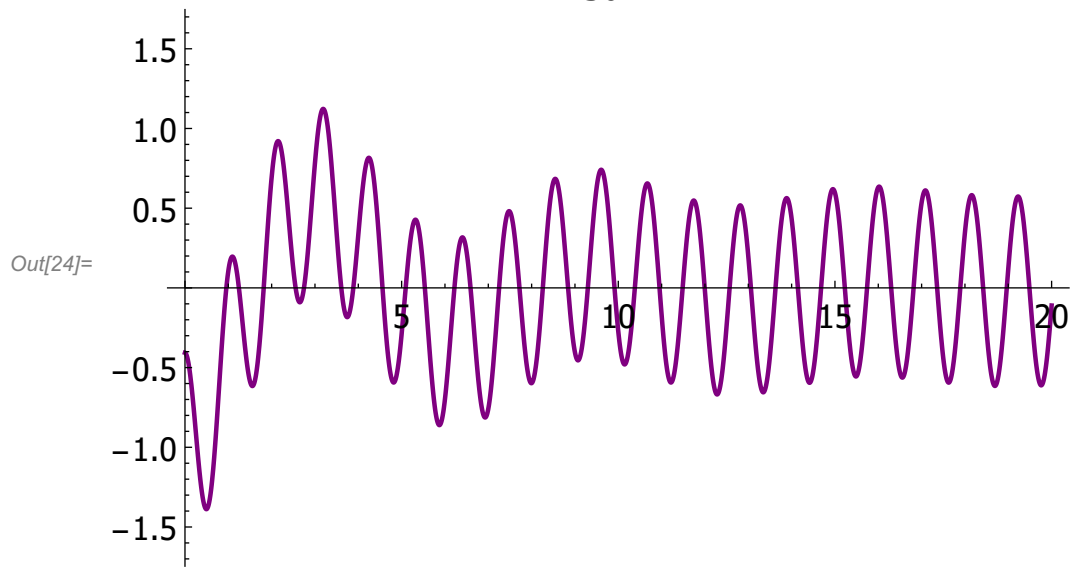
Sum

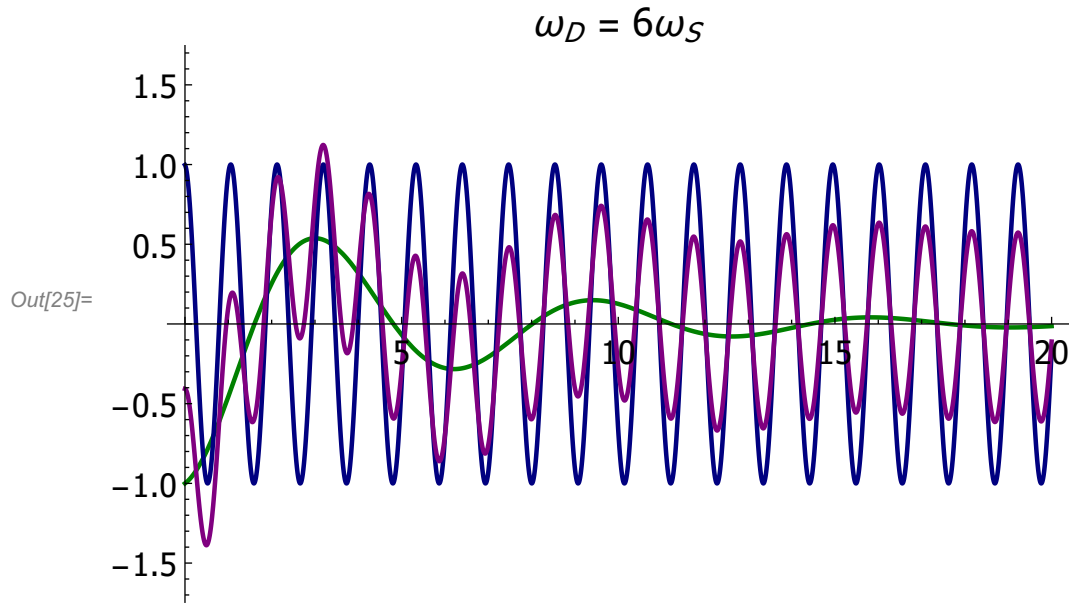


Steady State



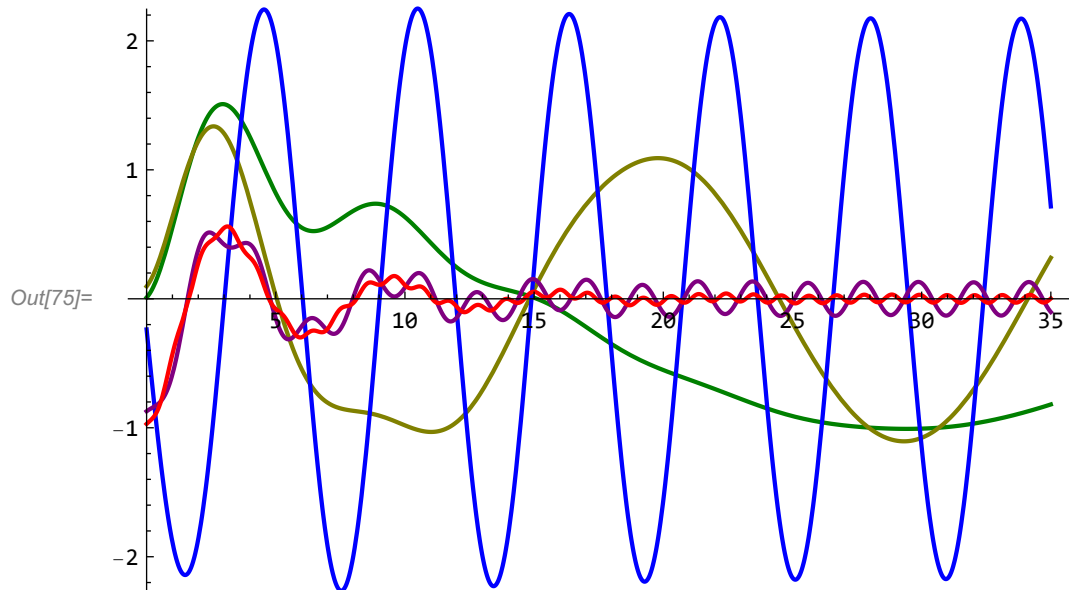
Sum



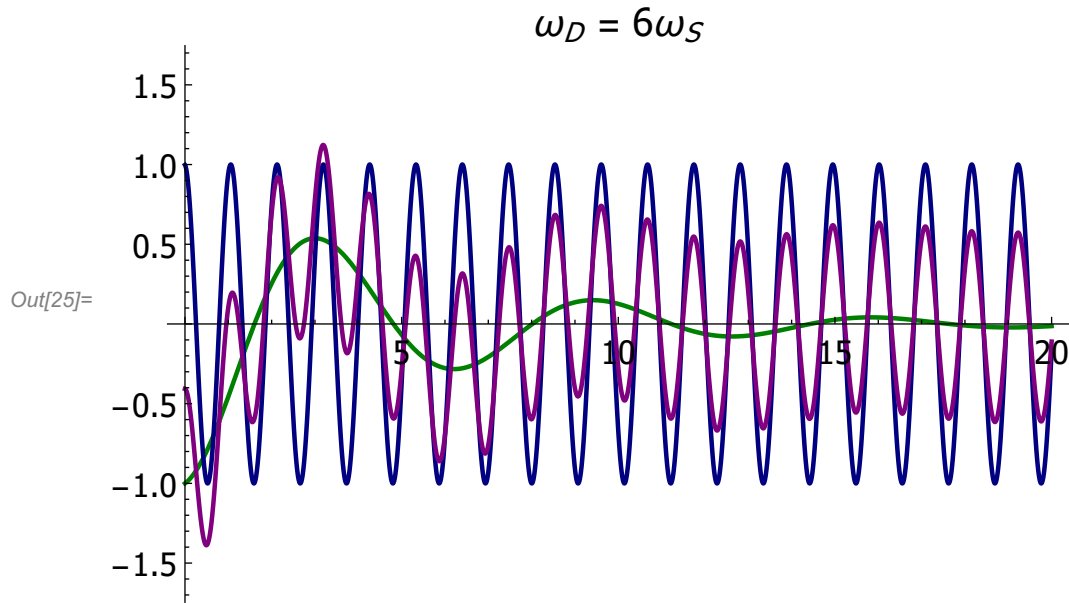


Plot just the sums for $\omega_D/\omega_S = 1/9, 1/3, 1.1, 3,$ and 6 .

```
In[75]:= Show[px1color, px2color, px3color, px4color, px5color, PlotRange -> All]
```

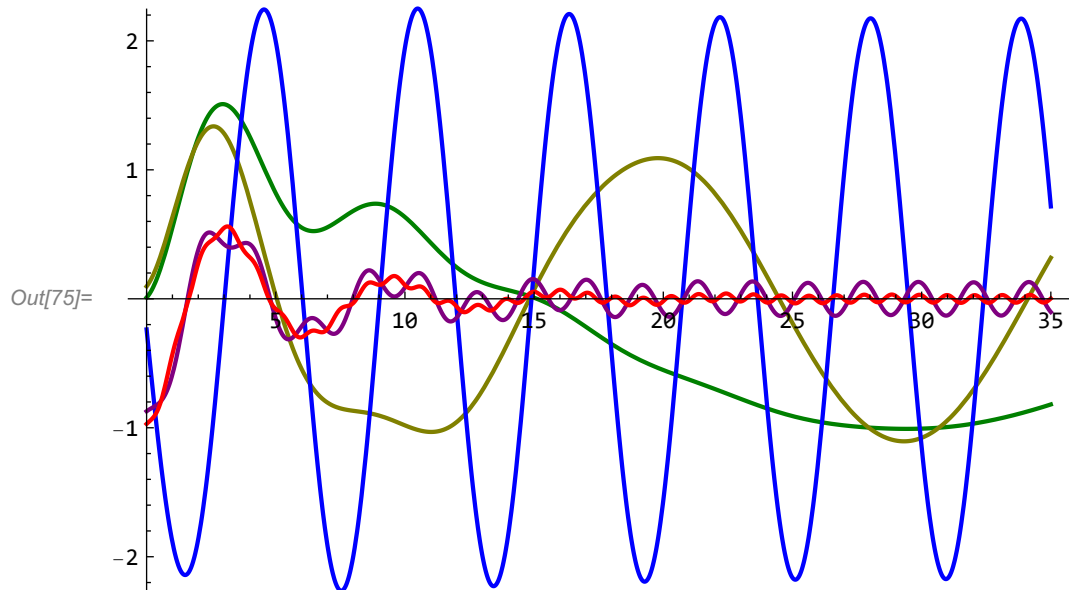


Since the amplitude of the steady-state function has $\sqrt{(\omega_S^2 - \omega_D^2)^2 - 4\beta^2 \omega_D^2}$ in the denominator, the amplitude of the steady state decreases as the difference between the frequencies increases ... the amplitude is greatest for the smallest difference, positive or negative! As for the warping, the first two (1/9 green, 1/3 olive) show the transient strongly warping the steady state. The last two (3 maroon, 6 red) show the steady state warping the transient. Both die out after about three system periods ($\tau_S=2\pi/\omega_S$) The $\omega_D/\omega_S = 1.1$ plot in blue shows the transient having very little effect on the steady state. So the transient has the greatest effect on steady state functions of increasing frequency difference, greater or lesser. The last plot of $\omega_D/\omega_S = 6$ with a larger steady state



Plot just the sums for $\omega_D/\omega_S = 1/9, 1/3, 1.1, 3,$ and 6 .

```
In[75]:= Show[px1color, px2color, px3color, px4color, px5color, PlotRange -> All]
```



Since the amplitude of the steady-state function has $\sqrt{(\omega_S^2 - \omega_D^2)^2 - 4\beta^2 \omega_D^2}$ in the denominator, the amplitude of the steady state decreases as the difference between the frequencies increases ... the amplitude is greatest for the smallest difference, positive or negative! As for the warping, the first two (1/9 green, 1/3 olive) show the transient strongly warping the steady state. The last two (3 maroon, 6 red) show the steady state warping the transient. Both die out after about three system periods ($\tau_S=2\pi/\omega_S$) The $\omega_D/\omega_S = 1.1$ plot in blue shows the transient having very little effect on the steady state. So the transient has the greatest effect on steady state functions of increasing frequency difference, greater or lesser. The last plot of $\omega_D/\omega_S = 6$ with a larger steady state

amplitude shows more strongly that the steady state warps the transient when it has a greater frequency.

```
In[1]:= Export["TM5Pr03_24Mathematica.pdf", SelectedNotebook[]]
```

```
Out[1]= TM5Pr03_24Mathematica.pdf
```

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```
In[1]:= Export["TM5Pr03_24Mathematica.pdf", SelectedNotebook[]]
```

```
Out[1]= TM5Pr03_24Mathematica.pdf
```